an oscillatory system that operates at super high frequencies; it is the analog of an oscillatory circuit.

The cavity resonator has the form of a volume filled with a dielectric—air, in most cases. The volume is bounded by a conducting surface or by a space having differing electrical or magnetic properties. Hollow cavity resonators—cavities enclosed by metal walls—are most widely used. Generally speaking, the boundary surface of a cavity resonator can have an arbitrary shape. In practice, however, only a few very simple shapes are used because such shapes simplify the configuration of the electromagnetic field and the design and manufacture of resonators. These shapes include right circular cylinders, rectangular parallelepipeds, toroids, and spheres. It is convenient to regard some types of cavity resonators as sections of hollow or dielectric wave guides limited by two parallel planes.

The solution of the problem of the natural (or normal) modes of oscillation of the electromagnetic field in a cavity resonator reduces to the solution of Maxwell's equations with appropriate boundary conditions. The process of storing electromagnetic energy in a cavity resonator can be clarified by the following example: if a plane wave is in some way excited between two parallel reflecting planes such that the wave propagation is perpendicular to the planes, then when the wave arrives at one of the planes, it will be totally reflected. Multiple reflection from the two planes produces waves that propagate in opposite directions and interfere with each other. If the distance between the planes is $L = n\lambda/2$, where λ is the wavelength and n is an integer, then the interference of the waves will produce a standing wave (Figure 1); the amplitude of this wave will increase rapidly if multiple reflections are present. Electromagnetic energy will be stored in the space between the planes. This effect is similar to the resonance effect in an oscillatory circuit.



Figure 1. Formation of standing wave in space between two parallel planes as a result of interference between direct wave and reflected wave

Normal oscillations can exist in a cavity resonator for an infinitely long time if there are no energy losses. However, in practice, energy losses in a cavity resonator are unavoidable. The alternating magnetic field induces electric currents on the inside walls of the resonator, which heat the walls and thus cause energy losses (conduction losses). Moreover, if there are apertures in the walls of the cavity and if these apertures intersect the lines of current, then an electromagnetic field will be generated outside the cavity, which causes energy losses by radiation. In addition, there are energy losses within the dielectric and losses caused by coupling with external circuits. The ratio of energy that is stored in a cavity resonator to the total losses in the resonator taken over one oscillation is called the figure of merit, or quality factor, or Q, of the cavity resonator. The higher the figure of merit, the better the quality of the resonator.

By analogy with wave guides, the oscillations that occur in a cavity resonator are classified in groups. In this classification, the grouping depends on the presence or absence of axial and radial (transverse) components in the spatial distribution of the electromagnetic field. Oscillations of the H (or TE) type have an axial component in the magnetic field only; oscillations of the E (or TM) type have an axial component in the electric field only. Finally, oscillations of the TEM type do not have axial components in either the electric or the magnetic field. An example of a cavity resonator in which TEM oscillations can be excited is the cavity between two conducting coaxial cylinders having end boundaries that are formed by plane conducting walls perpendicular to the axis of the cylinders.

Cylindrical cavity resonators are the most widely used type of cavity resonator. The types of oscillation in cylindrical cavity resonators are characterized by the three subscripts *m*, *n*, and *p* that correspond to the number of half waves of the electric or magnetic field that fit along the diameter, circumference, and length of the resonator, for instance, E_{mnp} or H_{mnp} . The type of oscillation (E or H) and the subscripts of the oscillation define the structure of the electric and the magnetic field in a resonator (Figure 2). The H_{011} mode of a cylindrical cavity resonator exhibits a peculiar property: it is quite insensitive to whether or not the cylindrical walls and the end walls are in contact. In this mode, the magnetic lines of force are directed (Figure 2, c) such that only currents along the lateral surface of the cylinder perpendicular to the axis are excited in the walls of the resonator. This fact makes it possible for nonradiating slots to be introduced into the side walls and end walls of the cavity.



Figure 2. Simplest modes of oscillation in a circular cylindrical hollow resonator: (a) E_{010} , (b) H_{111} , and (c) H_{011} . Solid lines denote lines of force of electric field; broken lines denote lines of force of magnetic field. The density of the lines of force is a measure of the field intensity. For the modes E_{010} and H_{111} , the density of the lines is a maximum on the axis of the cylinder (an antinode) and is equal to zero on the walls of the cylinder (a node). The lines of force of the magnetic field are closed curves.

Resonators of other shapes are sometimes used in addition to cylindrical cavity resonators; for instance, rectangular cavity resonators are used in laboratory equipment (Figure 3, a). Another important design is the toroidal cavity with a capacitive gap (Figure 3, b); this resonator is used for the oscillatory system of the klystron. The fundamental mode of such a cavity resonator is distinguished by the fact that the electric field and the magnetic field are spatially separated. The electric field is localized mainly in the capacitive gap, and the magnetic field in the toroidal cavity. The field distribution in dielectric cavity resonators is similar to the field distribution in hollow metal resonators of the same shape if the difference between the dielectric constant of

the resonator and that of the surrounding space is substantial. In contrast to hollow cavity resonators, the field of dielectric resonators does penetrate into the surrounding space. This field, however, is rapidly damped with increasing distance from the surface of the dielectric.



Figure 3. (a) Rectangular hollow cavity resonator in which fundamental mode E_{110} is excited; solid lines denote lines of force of electric field and broken lines denote lines of force of magnetic field; (b) toroidal resonator of klystron; (c) resonator system of magnetron

Hollow metal cavity resonators are usually made of metals that have a high electrical conductivity, such as silver and copper and their alloys, or else the inner surface of the resonator is coated with a layer of silver or gold. Cavity resonators with an extremely high figure of merit can be obtained by using superconducting metals (*see*CRYOELECTRONICS). A cavity resonator can be tuned to a given frequency by changing the volume of the cavity by moving the walls or by inserting metal plungers, plates, or other tuning elements into the cavity. Coupling to external circuits is usually carried out through apertures in the walls of the cavity with the aid of loops, probes, and other coupling components. Dielectrics with a high dielectric constant, such as rutile and strontium titanate, have low dielectric losses and are used for dielectric cavity resonators.

Cavity resonators are widely used in engineering as the oscillatory systems of generators (klystrons, magnetrons), as filters, as frequency standards, as measuring circuits, and in various devices designed for investigating solid, liquid, and gaseous substances. They can be used in the frequency range from 10^9 to 10^n hertz. At higher frequencies, the wavelength of the oscillations excited in a cavity resonator becomes comparable to the dimensions of the unavoidable surface defects on the walls of the cavity resonator. This fact causes a dissipation of the electromagnetic energy, a drawback that is eliminated in open resonators consisting of a system of mirrors.

WAVEGUIDE JUNCTION

Waveguide junctions are used when power in a waveguide needs to be split or some extracted. There are a number of different types of waveguide junction that can be use, each type having different properties - the different types of waveguide junction affect the energy contained within the waveguide in different ways.

When selecting a waveguide junction balances between performance and cost need to be made and therefore an understanding of the different types of waveguide junction is usedful. There are a number of different types of waveguide junction. The major types are listed below:

- **H-type T Junction:** This type of waveguide junction gains its name because top of the "T" in the T junction is parallel to the plane of the magnetic field, H lines in the waveguide.
- **E-Type T Junction:** This form of waveguide junction gains its name as an E- type T junction because the tope of the "T" extends from the main waveguide in the same plane as the electric field in the waveguide.
- **Magic T waveguide junction:** The magic T waveguide junction is effectively a combination of the E-type and H-type waveguide junctions.
- **Hybrid Ring Waveguide Junction:** This form of waveguide junction is another form of waveguide junction that is more complicated than either the basic E-type or H-type waveguide junction.

E-TYPE WAVEGUIDE JUNCTION

It is called an E-type T junction because the junction arm, i.e. the top of the "T" extends from the main waveguide in the same direction as the E field. It is characterized by the fact that the outputs of this form of waveguide junction are 180° out of phase with each other.



Waveguide E-type junction

The basic construction of the waveguide junction shows the three port waveguide device. Although it may be assumed that the input is the single port and the two outputs are those on the top section of the "T", actually any port can be used as the input, the other two being outputs.

To see how the waveguide junction operates, and how the 180° phase shift occurs, it is necessary to look at the electric field. The magnetic field is omitted from the diagram for simplicity.



It can be seen from the electric field that when it approaches the T junction itself, the electric field lines become distorted and bend. They split so that the "positive" end of the line remains with the top side of the right hand section in the diagram, but the "negative" end of the field lines remain with the top side of the left hand section. In this way the signals appearing at either section of the "T" are out of phase.

These phase relationships are preserved if signals enter from either of the other ports.

H-TYPE WAVEGUIDE JUNCTION

This type of waveguide junction is called an H-type T junction because the long axis of the main top of the "T" arm is parallel to the plane of the magnetic lines of force in the waveguide. It is characterized by the fact that the two outputs from the top of the "T" section in the waveguide are in phase with each other.



To see how the waveguide junction operates, the diagram below shows the electric field lines. Like the previous diagram, only the electric field lines are shown. The electric field lines are shown using the traditional notation - a cross indicates a line coming out of the screen, whereas a dot indicates an electric field line going into the screen.



It can be seen from the diagram that the signals at all ports are in phase. Although it is easiest to consider signals entering from the lower section of the "T", any port can actually be used - the phase relationships are preserved whatever entry port is ised.

MAGIC T HYBRID WAVEGUIDE JUNCTION

The magic-T is a combination of the H-type and E-type T junctions. The most common application of this type of junction is as the mixer section for microwave radar receivers.



Magic T waveguide junction

The diagram above depicts a simplified version of the Magic T waveguide junction with its four ports.

To look at the operation of the Magic T waveguide junction, take the example of whan a signal is applied into the "E plane" arm. It will divide into two out of phase components as it passes into the leg consisting of the "a" and "b" arms. However no signal will enter the "E plane" arm as a result of the fact that a zero potential exists there - this occurs because of the conditions needed to create the signals in the "a" and "b" arms. In this way, when a signal is applied to the H plane arm, no signal appears at the "E plane" arm and the two signals appearing at the "a" and "b" arms are 180° out of phase with each other.



Magic T waveguide junction signal directions

When a signal enters the "a" or "b" arm of the magic t waveguide junction, then a signal appears at the E and H plane ports but not at the other "b" or "a" arm as shown.

One of the disadvantages of the Magic-T waveguide junction are that reflections arise from the impedance mismatches that naturally occur within it. These reflections not only give rise to power loss, but at the voltage peak points they can give rise to arcing when sued with high power transmitters. The reflections can be reduced by using matching techniques. Normally posts or screws are used within the E-plane and H-plane ports. While these solutions improve the impedance matches and hence the reflections, they still reduce the power handling capacity.

HYBRID RING WAVEGUIDE JUNCTION

This form of waveguide junction overcomes the power limitation of the magic-T waveguide junction.

A hybrid ring waveguide junction is a further development of the magic T. It is constructed from a circular ring of rectangular waveguide - a bit like an annulus. The ports are then joined to the annulus at the required points. Again, if signal enters one port, it does not appear at allt he others.

The hybrid ring is used primarily in high-power radar and communications systems where it acts as a duplexer - allowing the same antenna to be used for transmit and receive functions.

During the transmit period, the hybrid ring waveguide junction couples microwave energy from the transmitter to the antenna while blocking energy from the receiver input. Then as the receive cycle starts, the hybrid ring waveguide junction couples energy from the antenna to the receiver. During this period it prevents energy from reaching the transmitter.

Waveguide junctions are an essential element within waveguide technology. Enabling signals to be combined and split, they find applications in many areas as discussed in the text. The waveguide T junctions are the simplest, and possibly the most widely used, although the magic-T and hybrid ring versions of the waveguide junction are used in particular applications where their attributes are required.

WAVEGUIDE FLANGES, COUPLERS AND TRANSITIONS

A signal can be entered into the waveguide in a number of ways. The most straightforward is to use what is known as a launcher. This is basically a small probe which penetrates a small distance into the centre of the waveguide itself as shown. Often this probe may be the centre conductor of the coaxial cable connected to the waveguide. The probe is orientated so that it is parallel to the lines of the electric field which is to be set up in the waveguide. An alternative method is to have a loop which is connected to the wall of the waveguide. This encompasses the magnetic field lines and sets up the electromagnetic wave in this way. However for most applications it is more convenient to use the open circuit probe. These launchers can be used for transmitting signals into the waveguide as well as receiving them from the waveguide.



WAVEGUIDE BENDS

Waveguide is normally rigid, except for flexible waveguide, and therefore it is often necessary to direct the waveguide in a particular direction. Using waveguide bends and twists it is possible to arrange the waveguide into the positions required.

When using waveguide bends and waveguide twists, it is necessary to ensure the bending and twisting is accomplished in the correct manner otherwise the electric and magnetic fields will be unduly distorted and the signal will not propagate in the manner required causing loss and reflections. Accordingly waveguide bend and waveguide twist sections are manufactured specifically to allow the waveguide direction to be altered without unduly destroying the field patterns and introducing loss.

Types of waveguide bend

There are several ways in which waveguide bends can be accomplished. They may be used according to the applications and the requirements.

- Waveguide E bend
- Waveguide H bend
- Waveguide sharp E bend •
- Waveguide sharp H bend

Each type of bend is achieved in a way that enables the signal to propagate correctly and with the minimum of disruption to the fields and hence to the overall signal.

Ideally the waveguide should be bent very gradually, but this is normally not viable and therefore specific waveguide bends are used.

Most proprietary waveguide bends are common angles - 90° waveguide bends are the most common by far.

Waveguide E bend

This form of waveguide bend is called an E bend because it distorts or changes the electric field to enable the waveguide to be bent in the required direction.



Waveguide E bend

To prevent reflections this waveguide bend must have a radius greater than two wavelengths.

Waveguide H bend

This form of waveguide bend is very similar to the E bend, except that it distorts the H or magnetic field. It creates the bend around the thinner side of the waveguide.



As with the E bend, this form of waveguide bend must also have a radius greater than 2 wavelengths to prevent undue reflections and disturbance of the field.

Waveguide sharp E bend

In some circumstances a much shorter or sharper bend may be required. This can be accomplished in a slightly different manner. The techniques are to use a 45° bend in the waveguide. Effectively the signal is reflected, and using a 45° surface the reflections occur in such a way that the fields are left undisturbed, although the phase is inverted and in some applications this may need accounting for or correcting.



Waveguide sharp H bend

This for of waveguide bend is the same as the sharp E bend, except that the waveguide bend affects the H field rather than the E field.



WAVEGUIDE TWISTS

There are also instances where the waveguide may require twisting. This too, can be accomplished. A gradual twist in the waveguide is used to turn the polarization of the waveguide and hence the waveform.

In order to prevent undue distortion on the waveform a 90° twist should be undertaken over a distance greater than two wavelengths of the frequency in use. If a complete inversion is required, e.g. for phasing requirements, the overall inversion or 180° twist should be undertaken over a four wavelength distance.

Waveguide bends and waveguide twists are very useful items to have when building a waveguide system. Using waveguide E bends and waveguide H bends and their srap bend counterparts allows the waveguide to be turned through the required angle to meet the mechanical constraints of the overall waveguide system. Waveguide twists are also useful in many applications to ensure the polarization is correct.

ATTENUATOR:

A *microwave circulator* is a multiport waveguide junction in which the wave can flow only from the nth port to the (n + 1)th port in one direction (see Fig. 4-6-2). Although there is no restriction on the number of ports, the four-port microwave circulator is the most common. One type of four-port microwave circulator is a combination of two 3-dB side-hole directional couplers and a rectangular waveguide with two nonreciprocal phase shifters as shown in Fig. 4-6-3.



The operating principle of a typical microwave circulator can be analyzed with the aid of Fig. 4-6-3. Each of the two 3-dB couplers in the circulator introduces a phase shift of 90°, and each of the two phase shifters produces a certain amount of phase change in a certain direction as indicated.

When a wave is incident to port 1, the wave is split into two components by coupler **1**. The wave in the primary guide arrives at port 2 with a relative phase change of 180° . The second wave propagates through the two couplers and the secondary guide and arrives at port 2 with a relative phase shift of 180° .

Since the two waves reaching port 2 are in phase, the power transmission is obtained from port 1 to port

2. However, the wave propagates through the primary guide, phase shifter, and coupler 2 and arrives at port 4 with a phase change of 270° . The wave travels through coupler 1 and the secondary guide, and it arrives at port 4 with a phase shift of 90° . Since the two waves reaching port 4 are out of phase by 180° , the power transmission from port 1 to port 4 is zero.

In general, the differential propagation constants in the two directions of propagation in a waveguide containing ferrite phase shifters should be where m and n are any integers, including zeros. A similar analysis shows that a wave incident to port 2 emerges at port 3 and so on. As a result, the sequence of power flow is designated as $1 \sim 2 \sim 3 \sim 4 \sim 1$. Many types of microwave circulators are in use today.

However, their principles of operation remain the same. Figure 4-6-4 shows a four-port circulator constructed of two magic tees and a phase shifter. The phase shifter produces a phase shift of 180°. The explanation of how this circulator works is left as an exercise for the

reader.

DIRECTIONAL COUPLERS:

A directional coupler is a four-port waveguide junction as shown in Fig. 4-5-1. It consists of a primary waveguide 1-2 and a secondary waveguide 3-4.

When all ports are terminated in their characteristic impedances, there is free transmission of power, without reflection, between port 1 and port 2, and there is no transmission of power between port 1 and port 3 or between port 2 and port 4 because no coupling exists between these two pairs of ports.

The degree of coupling between port 1 and port 4 and between port 2 and port 3 depends on the structure of the coupler. The characteristics of a directional coupler can be expressed in terms of its coupling factor and its directivity.

Assuming that the wave is propagating from port 1 to port 2 in the primary line, the coupling factor and the directivity are defined,



respectively, by

Coupling factor (dB) = 10
$$\log_{10} \frac{P_1}{P_4}$$

Directivity (dB) = 10 $\log_{10} \frac{P_4}{P_*}$

where P_{i} = power input to port 1

P3 = power output from port 3 P4 = power output from port 4

It should be noted that port 2, port 3, and port 4 are terminated in their characteristic impedances. *The coupling factor is* a measure of *the ratio* of power levels in the primary and secondary lines. Hence if the coupling factor is known, a fraction of power measured at port 4 may be used to determine the power input at port

- 1. This significance is desirable for microwave power measurements because no disturbance, which may be caused by the power measurements, occurs in the primary line.
- 2. The directivity is a measure of how well the forward traveling wave in the primary waveguide couples only to a specific port of the secondary waveguide. An ideal directional coupler should have infinite directivity. In other words, the power at port 3 must be zero because port 2 and port 4 are perfectly matched.
- 3. Actually, well-designed directional couplers have a directivity of only 30 to 35 dB. Several types of directional couplers exist, such as a two-hole directional couler, four-hole directional coupler, reverse-coupling directional coupler (Schwinger coupler), and Bethe-hole directional coupler (refer to Fig. 4-5-2). Only the very commonly used two-hole directional coupler is described here.



Figure 4-5-2 Different directional couplers. (a) Two-hole directional coupler. (b) Four-hole directional coupler. (c) Schwinger coupler. (d) Bethe-hole directional coupler.

 $S_{11} = S_{22} = S_{33} = S_{44} = 0$

As noted, there is no coupling between port 1 and port 3 and between port 2 and port 4. Thus