

# [PERT] PROGRAM EVALUATION REVIEW TECHNIQUE

- ① PERT is an event oriented Network - that was developed by U.S Navy.
- ② It is used in those type of project in which precise determination of time can't be made such as →
  - ① R.M.D (Research and development)
  - ② Non - (Repetative type project)
- ③ It is based on probabilistic approach.
- ④ Cost of the project is directly proportional to time.

Time Estimate: - In order to account the uncertainty in the completion time of activities

There are three time estimates in PERT Network

① Optimistic time [ $t_o$ ]: - It is the minimum time in which activity may be expected to be completed under most ideal condition.

② Pessimistic time [ $t_p$ ]: - It is the maximum time in which an activity may be expected to be completed under most adverse condition.



3) Most likely time ( $t_m$ ) :- It is the time in which the activity is normally completed under normal condition.

Note :- ① In a project there may be many activities. In PERT Network probability distribution curve of each activity is  $\beta$ -distribution curve, but for the entire project probability distribution curve is normal-distribution curve.

It symmetrical curve then normal-distrib.  
If not symmetrical curve then  $\beta$ -dist.

② Expected time / Mean time of an Activity :- It is that time in which probability of completion of project is 50%.

$$t_e = \frac{t_o + 4t_m + t_p}{6}$$

③ Standard deviation of an Activity :-

$$\sigma = \frac{t_p - t_o}{6}$$

④ Variance of an Activity :- Uncertainty for

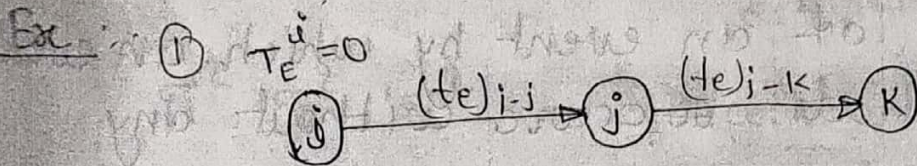
$$\text{Variance} = \sigma^2 = \left( \frac{t_p - t_o}{6} \right)^2$$



Variance represent the uncertainty of the completion of project. Higher value of variance represent more uncertainty

## EVENT TIME

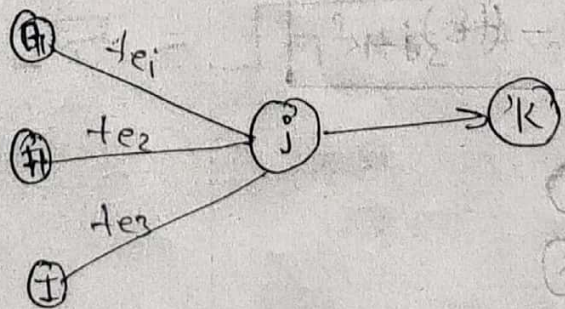
① EARLIEST EXPECTED TIME :- This is the minimum time in which the event may occur. An event occurs only when all the predecessor activity are completed.



$$T_E^j = T_E^i + (te)_{i-j}$$

$(T_E)_{\text{successor Event}} = (T_E)_{\text{predecessor event}} + \text{Activity duration}$

So  $T_E^k = T_E^j + (te)_{j-k}$

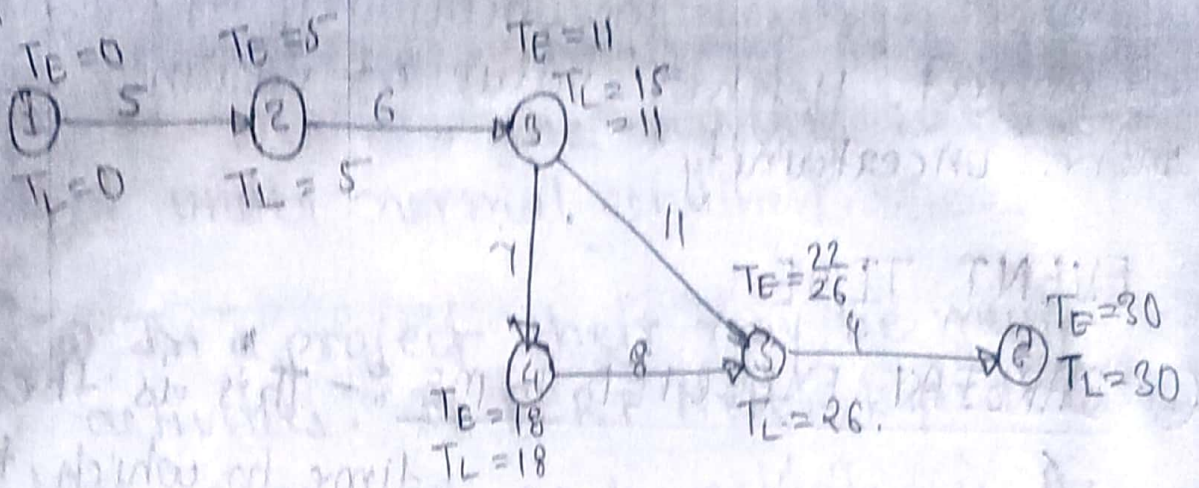


$$(T_E)^j = \left[ (T_E)_{\text{predecessor event}} + \text{Activity duration} \right]_{\text{max}}$$

So,  $T_E^j = T_E^{G1} + (te)_{G1-j}$   
 or  $T_E^j = T_E^{G2} + (te)_{G2-j}$   
 or  $T_E^j = T_E^{G3} + (te)_{G3-j}$  } merge



Question



Latest Allowable Occurance time: It is the max. time or latest time of an event by which an event may be allowed to occur without any delay in completion of project.

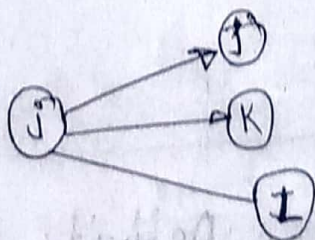
$$(TL)_{\text{predecessor Event}} = (TL)_{\text{successor Event}} - \text{Activity Duration}$$

Ex-1



$$(TL)_j = (TL)_k - (te)_{j-k}$$

Ex-2



$$(TL)_i = \begin{matrix} TL^j - (te)_{i-j} \\ \text{or } TL^k - (te)_{i-k} \\ \text{or } TL^l - (te)_{i-l} \end{matrix} \text{ mini.}$$